

The differential operator notation used in this document is 'D', not 'p'.

$$\psi_{d0}\Delta_{\delta}(t) + \frac{\psi_{q0}D\Delta_{\delta}(t)}{\omega_0} = \frac{D\Delta_{\psi_d}(t)}{\omega_0} - \Delta_{\psi_q}(t) \quad (\text{e5.9})$$

$$\Delta_{\delta}(t) = \frac{\frac{D\Delta_{\psi_d}(t)}{\omega_0} - \Delta_{\psi_q}(t)}{\psi_{d0} + \frac{\psi_{q0}D}{\omega_0}} \quad (\text{e5.11})$$

$$\psi_{q0}\Delta_{\delta} = \frac{1}{\omega_0} p(\Delta_{\psi_q}) + \Delta_{\psi_d} + \psi_{d0} \frac{1}{\omega_0} p(\Delta_{\delta}) \quad (\text{e5.10})$$

$$\Delta_{\psi_d}(t) = \psi_{q0}\Delta_{\delta}(t) - \frac{D\Delta_{\psi_q}(t)}{\omega_0} - \frac{\psi_{d0}D\Delta_{\delta}(t)}{\omega_0} \quad (\text{e5.12})$$

Substituting Equation (e5.12) in (e5.11), rearranging and simplifying:

$$\Delta_{\delta}(t) = \frac{\psi_{q0}D\Delta_{\delta}(t)}{\left(\psi_{d0} + \frac{\psi_{q0}D}{\omega_0}\right)\omega_0} - \frac{D^2\Delta_{\psi_q}(t)}{\left(\psi_{d0} + \frac{\psi_{q0}D}{\omega_0}\right)\omega_0^2} - \frac{D^2\psi_{d0}\Delta_{\delta}(t)}{\left(\psi_{d0} + \frac{\psi_{q0}D}{\omega_0}\right)\omega_0^2} - \frac{\Delta_{\psi_q}(t)}{\psi_{d0} + \frac{\psi_{q0}D}{\omega_0}} \quad (\text{e5.13p})$$

The derivative of constant is 0 and the D and D<sup>2</sup> terms can be ignored, then the expression above becomes:

$$\psi_{d0}\Delta_{\delta} = -\Delta_{\psi_q} \quad (\text{e5.13})$$